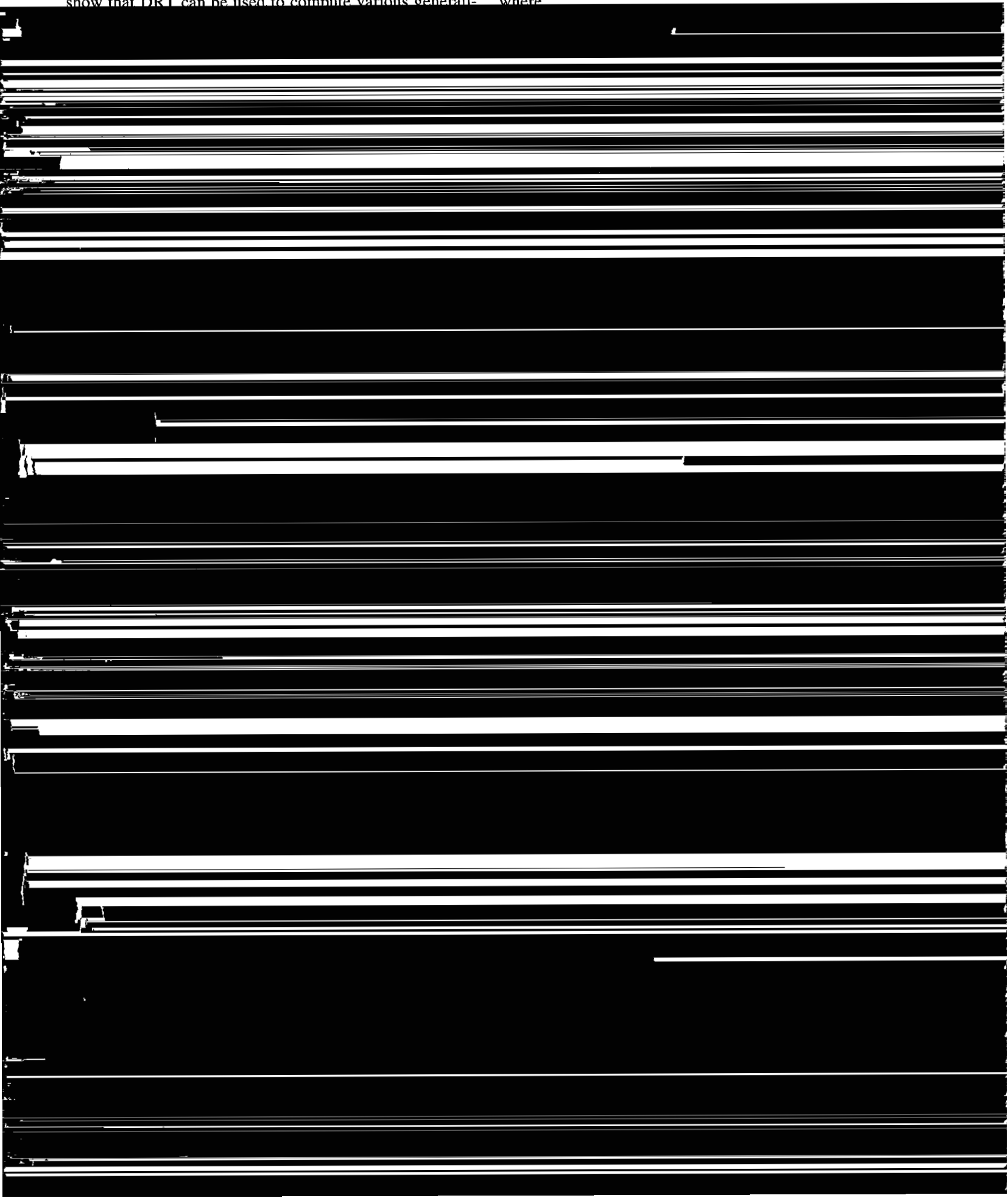


Discrete Radon Transform

GREGORY BEYLKIN

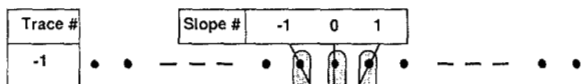
Abstract—This paper describes the discrete Radon transform (DRT) and the corresponding inversion algorithm for it. Similar to the continuous case, various discretizations of Radon's inversion formula. We

show that DRT can be used to compute various generali- where



$$\boxed{x_L(n)}$$

sets of points of the lattice with a weight coefficient assigned to each point. The family of objects is constructed



This is the key observation which follows from the periodicity condition (i). (Discussion of properties of the block-circulant matrices can be found in [27] for exam-

It follows from (4.6) that if $\sigma = 1$, matrices R_m are given by

$$(R_m)_{jl} = \delta_{m,jl}.$$

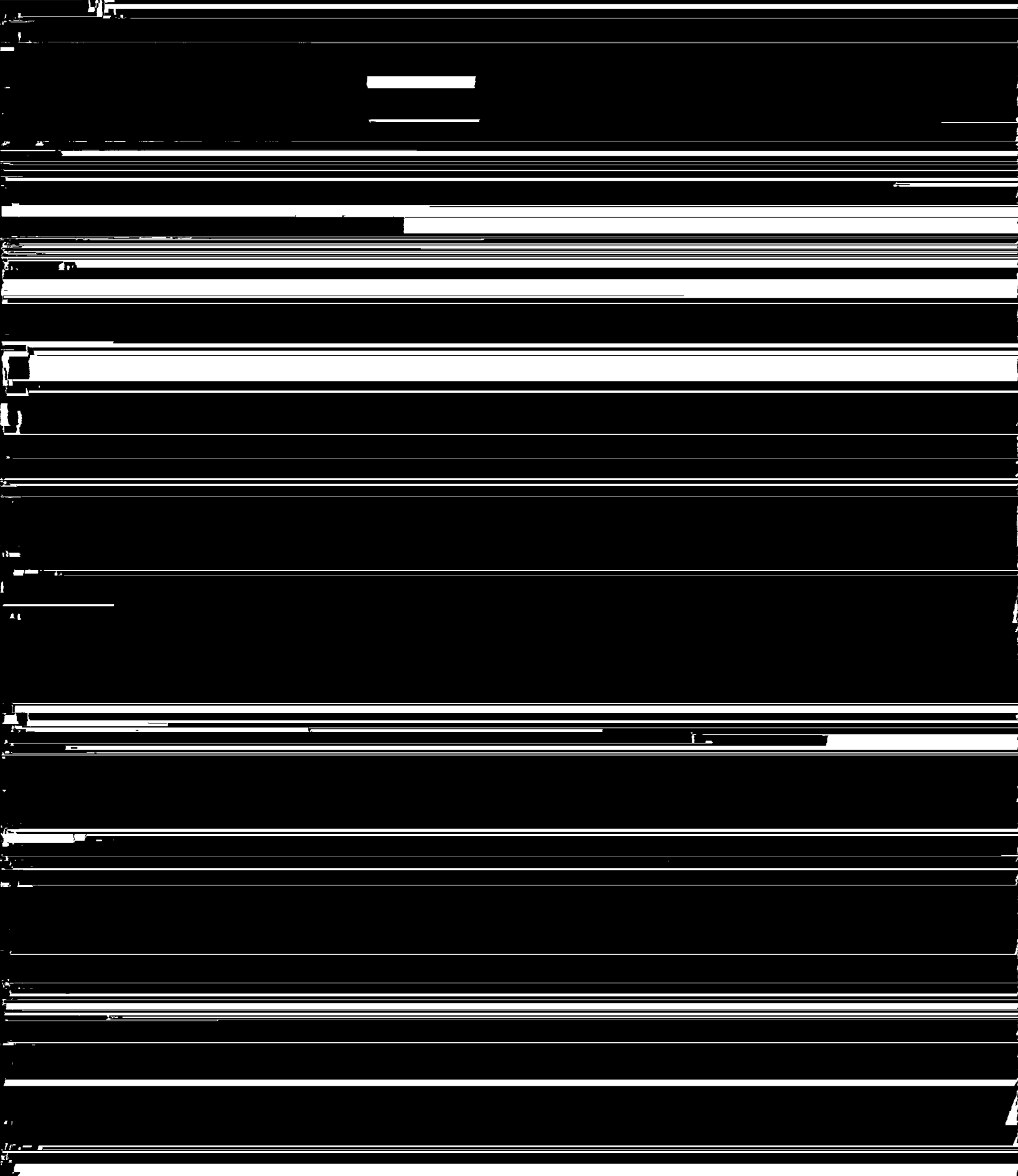
where $j = 0, \pm 1, \dots, \pm J$. This transform reduces to the ordinary DFT for $\alpha = 1$ and $L = J$. We consider now the following problem: given α and $\hat{w}_\alpha(j)$ for $j = 0, \pm 1, \dots, \pm J$, find $w(l)$. To solve this problem, we ap-

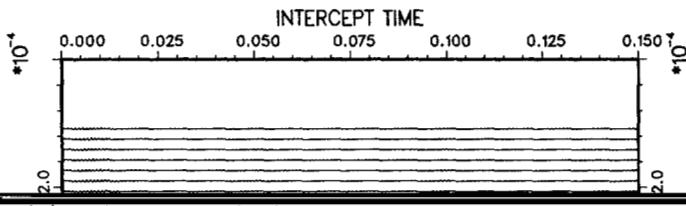
$= N/k_0(2J + 1)$, where $k_{\min} \leq k_0 \leq k_{\max}$, estimates of the eigenvalues of the matrix $\hat{H}_{L_{\infty}}(k)$ can be obtained using

Inversion formula (6.1) also implies the discrete Parseval's identity. In the continuous case, Parseval's iden-

One can see now that the expression in (4.8) is a discrete analog of the kernel in the inner integral in (7.2). If we

0.000 0.025 0.050 TIME 0.075 0.100 0.125 0.150

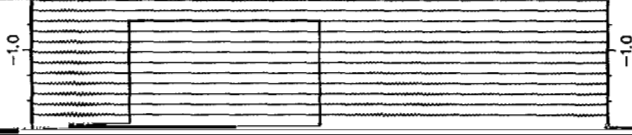




mask and the approximate inversion was a problem in using the tau- \mathcal{P} representation for the velocity filtering.

APPENDIX

Lemma 1 and Lemma 2 are essentially similar. Their proof is elementary. We use the notation of Lemma 1.



$$\hat{z}(k) = \sum_{m=-2M} H_m \sum_{n=0} x(n+m) e^{2\pi i(nk/N)},$$

or

